

Long-Lasting Colonies

Workshop on Revolutionary Aerospace System Concepts for Human/Robotic Exploration of the Solar System November 6, 2001

Wendell H Chun
Lockheed Martin/Colorado School of Mines

1

Lockheed Martin Robotics

- Past Key Programs
 - Intelligent Task Automation
 - Autonomous Land Vehicle
 - Mars Rovers
 - Flight Telerobotic Servicer
 - Unmanned Ground Vehicle Demo II Program
 - Intelligent Mobile Sensing System
 - Automated Highway System

Mars Rover Programs

- Understanding mobility (soft soil, inclines, crevices, obstacle negotiation)
- Power consumption as a function of mobility



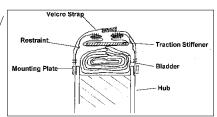
Unmanned Ground Vehicle (UGV) - Demo II

- Autonomous Navigation
- Planning and Re-planning for Contingencies
- Obstacle Detection
- Terrain Maps & Negative Obstacles
- Vehicle safety



Mobile Lander Prototype





Lockheed Martin Mobile Lander

- Issue 1: Combine the functionality of the lander with the rover into one vehicle
- Issue 2: Inflatable wheels to facilitate packaging

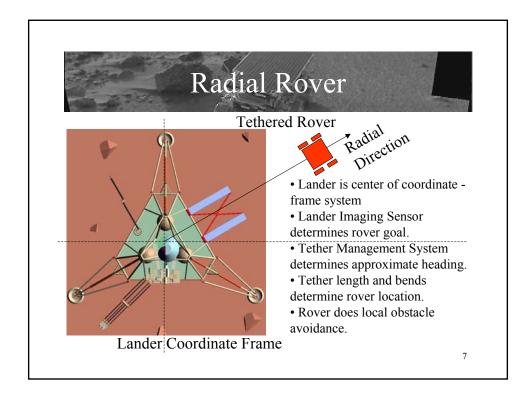


Inflatable Wheels

5

Lockheed Martin Robotics

- Current programs
 - Investigating Rovers under Mars Sample Return Study Contract
 - Phase 1B of DARPA's Unmanned Ground Combat Vehicle (UGCV)
 - Future Combat System
 - Orbital Express



Robotics Today

- Unmanned vehicles ideal for precursor mission
- Robots More robust than humans
- Processing Following Moore's Law
- Autonomous and Intelligent

Current Rover Issues

- Communications
- Power
- Mobility
- Navigation
- Payload
- On-board Processing
- Packaging

9

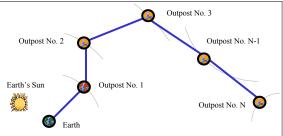
Long-Lasting Robots

- While humans are currently limited in space travel, why not send robots to build these outposts while we solve the problems of human flight?
- Even if we don't get to them in the next 40 years, someday we will require the use of these outposts.

Outpost Architecture

- If future propulsion technology cannot allow man to travel directly to his solar system destination in a direct and timely manner, stopping points will be required.
- These stopping points will function as waypoints or outposts. To reach any far destination, future space explorers will have to rely on these outposts.
- They can offer fuel, shelter, supplies, and possibly human food.
- Eventually, a network of outposts will be required for NASA to grow out of

our own solar system.



Long-Lasting Robot Issues

- Why can't a robot survive and adapt and operate for a hundred years and be productive?
- What will the places look like?



• When humans arrive, can humans work with the robot colony?

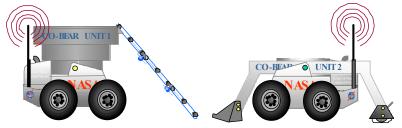
Attributes of Concept

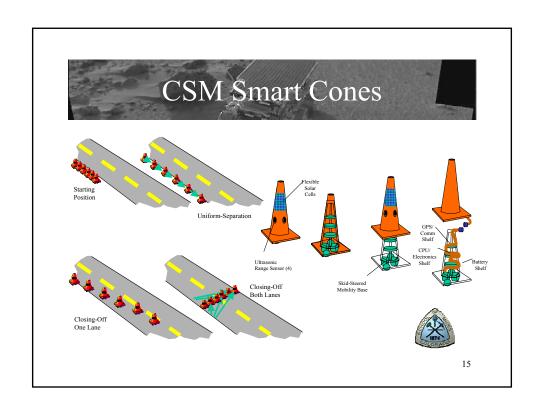
- Robot Colony
- Human/Robot Collaboration
- Long-Life Robots
- Autonomy
- Survivability & Repair
- Cooperative Robots
- Human-Robot Interaction

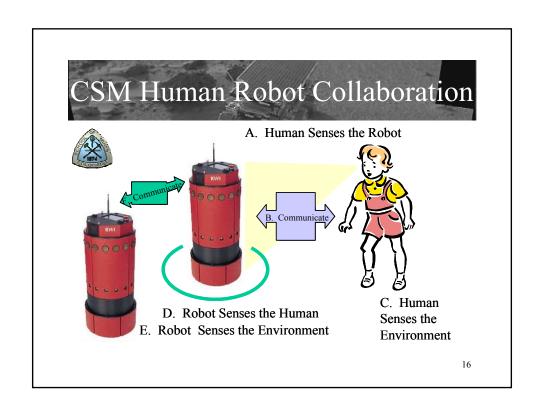
13

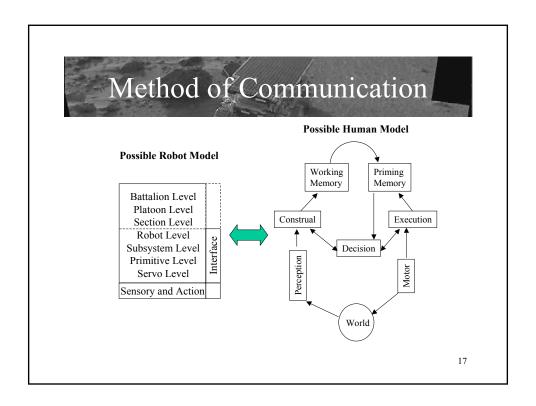
Proposed Team of Mining Robots

- Collaborative Robots
- Autonomous Operations
- Long Life









Summary

- Robots that could operate autonomously and for extremely long periods of time would be very beneficial to building infrastructure for human exploration of the solar system.
- The robot translator/communicator is needed to enable a human to communicate effectively with the robot and vice versa.
- It is possible to speed up the number of outposts in this architecture if robots could somehow build more robots.